

```

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```

Module
RX_Service.c

Revision
1.0.1

Description
This implements parsing of data from audio

Notes

History

When	Who	What/Why
05/17/20	LG	instituted CheckSum and updated based on state machine
05/16/20	LG	tried out a simpler version of receive (one sample based on timeout)
05/06/20 08:22	hbf	began conversion for Lab 10
01/16/12 09:58	jec	began conversion from TemplateFSM.c

```

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```

/*----- Include Files -----*/
/* include header files for this state machine as well as any machines at the
   next lower level in the hierarchy that are sub-machines to this machine
*/

```

```

#include "ES_Configure.h"
#include "ES_Framework.h"
#include "ES_Port.h"
#include "RX_Service.h"
#include "MicInputService.h"
#include "dbprintf.h"
#include "LED_Service.h"
#include "MicInputService.h"
#include "DataParserService.h"
#include "GameplayFSM.h"

```

```

/*----- Module Defines -----*/

```

```

#define BIT_TIME 10
#define HALF_BIT_TIME 5
#define NUM_DATA_DIBITS 10
#define FULL_SLOT_TIME 130

```

```

/*----- Module Functions -----*/
/* prototypes for private functions for this service.They should be functions
   relevant to the behavior of this service
*/

```

```

static void GetNextBit(void);

```

```

/*----- Module Variables -----*/
// with the introduction of Gen2, we need a module level Priority variable

```

```

static uint8_t MyPriority;
static uint8_t CurrentState;
static bool Starting = false;
static uint8_t RX_Counter;
static uint32_t RX_Data;
static uint32_t RX_ShiftReg;
static uint32_t Sum;

```

```

/*----- Module Code -----*/

```

```

*****

```

Function
InitRXService

Parameters
uint8_t : the priority of this service

Returns
bool, false if error in initialization, true otherwise

Description

Saves away the priority, and does any other required initialization for this service

Notes

Author

H. Francis, 05/08/20, 10:00

*****/

```
bool InitRXService(uint8_t Priority)
```

```
{
    ES_Event_t ThisEvent;

    MyPriority = Priority;
    CurrentState = RX_Idle;

    // post the initial transition event
    ThisEvent.EventType = ES_INIT;
    if (ES_PostToService(MyPriority, ThisEvent) == true)
    {
        return true;
    }
    else
    {
        return false;
    }
}
```

*****/

Function

PostRXService

Parameters

EF_Event_t ThisEvent ,the event to post to the queue

Returns

bool false if the Enqueue operation failed, true otherwise

Description

Posts an event to this state machine's queue

Notes

Author

H. Francis, 05/08/20, 10:00

*****/

```
bool PostRXService(ES_Event_t ThisEvent)
```

```
{
    return ES_PostToService(MyPriority, ThisEvent);
}
```

*****/

Function

RunRXService

Parameters

ES_Event_t : the event to process

Returns

ES_Event, ES_NO_EVENT if no error ES_ERROR otherwise

Description

Handles state machine for this service. Handles receiving a series of bits

Notes

Author

H. Francis, 05/08/20, 10:15

*****/

```
ES_Event_t RunRXService(ES_Event_t ThisEvent)
```

```
{
```

```

ES_Event_t ReturnEvent;
ReturnEvent.EventType = ES_NO_EVENT; // assume no errors
ES_Event_t PostEvent;

switch (CurrentState)
{
case RX_Idle:
{
if(ThisEvent.EventType == ES_START_LISTENING)
{
EnableListen();
CurrentState = RX_Listening;
}
if(ThisEvent.EventType == ES_TIMEOUT && ThisEvent.EventParam == RX_TIMER) {
EnableListen();
CurrentState = RX_Listening;
}
if(ThisEvent.EventType == ES_TIMEOUT && ThisEvent.EventParam == SERVO_RELEASE_TIMER) {
PostEvent.EventType = ES_START_LISTENING;
PostRXService(PostEvent);
}
}
}
break;
case RX_Listening:
{
if(ThisEvent.EventType == ES_START_BIT_DETECTED)
{
Starting = true; // not used in current code version for same reason as ^
RX_Counter = 0;
RX_ShiftReg = 0;
CurrentState = RX_Receiving;
}
if(ThisEvent.EventType == ES_STOP_LISTENING)
{
DisableListen();
CurrentState = RX_Idle;
}
}
}
break;
case RX_Receiving:
{
if(ThisEvent.EventType == ES_TIMEOUT && ThisEvent.EventParam == RX_TIMER)
{
if(Starting) { // for same reason as earlier comments, this is technically going unexecuted
Starting = false;
if(QueryBitState() == DIBIT_3) //good start bit
{
RX_ShiftReg = 0;
ES_Timer_InitTimer(RX_TIMER, BIT_TIME);
ES_Timer_InitTimer(TDMA_CLOCK, FULL_SLOT_TIME-HALF_BIT_TIME);
} else { //bad start bit
CurrentState = RX_Listening;
ClearFirstTime();
}
} else { //past start bit
GetNextBit();
}
}
}
if(ThisEvent.EventType == ES_EOR)
{
CurrentState = RX_Idle;
RX_ShiftReg = 0;
Sum = 0;
ClearFirstTime();
}
}
if(ThisEvent.EventType == ES_BAD_RECEPTION)
{

```

```

    CurrentState = RX_Listening;
    RX_ShiftReg = 0;
    Sum = 0;
    ClearFirstTime();
}
}
break;
}
return ReturnEvent;
}
/*****

```

Function
GetNextBit

Parameters
none

Returns
none

Description
helper function that handles collection of bits, validates the CheckSum, and updates the RX_Data variable

Notes

Author
L. Gardner, 05/16/20

*****/

static void GetNextBit(void)

```

{
    ES_Event_t PostEvent;
    uint8_t BitState = QueryBitState();

    if(RX_Counter < NUM_DATA_DIBITS)
    {
        ES_Timer_InitTimer(RX_TIMER, BIT_TIME);
        RX_Counter++;
        if (BitState == DIBIT_0)
        {
            RX_ShiftReg &= (BIT0LO & BIT1LO);
            RX_ShiftReg = RX_ShiftReg << 2;
            Sum += 0;
        }
        else if (BitState == DIBIT_1)
        {
            //printf("Detected Data bit..... 1\n\r");
            RX_ShiftReg |= BIT0HI;
            RX_ShiftReg = RX_ShiftReg << 2;
            Sum += 1;
        }
        else if (BitState == DIBIT_2)
        {
            //printf("Detected Data bit..... 2\n\r");
            RX_ShiftReg |= BIT1HI;
            RX_ShiftReg = RX_ShiftReg << 2;
            Sum += 2;
        }
        else if (BitState == DIBIT_3)
        {
            //printf("Detected Data bit..... 3\n\r");
            RX_ShiftReg |= (BIT1HI | BIT0HI);
            RX_ShiftReg = RX_ShiftReg << 2;
            Sum += 3;
        }
    }
    else {
        uint8_t CheckSum = 0;
        Sum &= (BIT1HI | BIT0HI);
    }
}

```

```

Checksum = 3-Sum;
if(BitState != CheckSum) { //framing error
    printf("BAD DATA\n\r");
} else {
    RX_Data = RX_ShiftReg;
    ConvertFromPacket(RX_Data>>2);
    printf("GOOD DATA \n\r");
}
PostEvent.EventType = ES_EOR;
PostRXService(PostEvent);
PostGameplayFSM(PostEvent);
ES_Timer_InitTimer(RX_TIMER, HALF_BIT_TIME);
DisableListen();
}
}
}
/*****

```

Function
GetRX_Data

Parameters
none

Returns
RX_Data

Description
getter function for the DataParser to call

Notes

Author
L. Gardner, 05/16/20

```

/*****
uint32_t GetRX_Data(void) {
    return RX_Data;
}
/*****

```

Function
GetRXState

Parameters
none

Returns
RX state

Description
getter function for RXState

Notes

Author
L. Gardner, 05/16/20

```

/*****
RX_State_t GetRXState(void){
    return CurrentState;
}

```

/*----- Footnotes -----*/
/*----- End of file -----*/